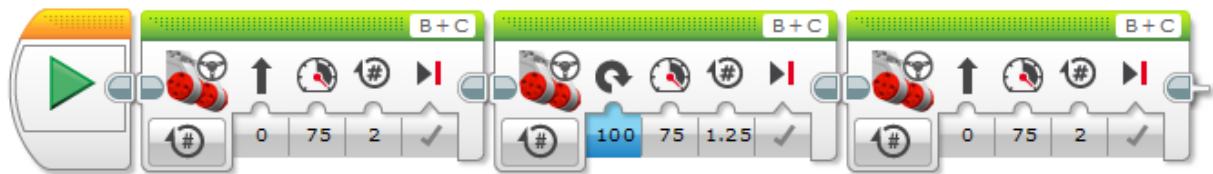


This program will make the robot drive forward and then backward



This program will make the robot drive in a circle

